



A UNIVERSAL, LOW-COST TRANSRADIAL SOCKET FOR VALIDATING NOVEL MYOELECTRIC PROSTHETIC CONTROL STRATEGIES



THE UNIVERSITY OF UTAH

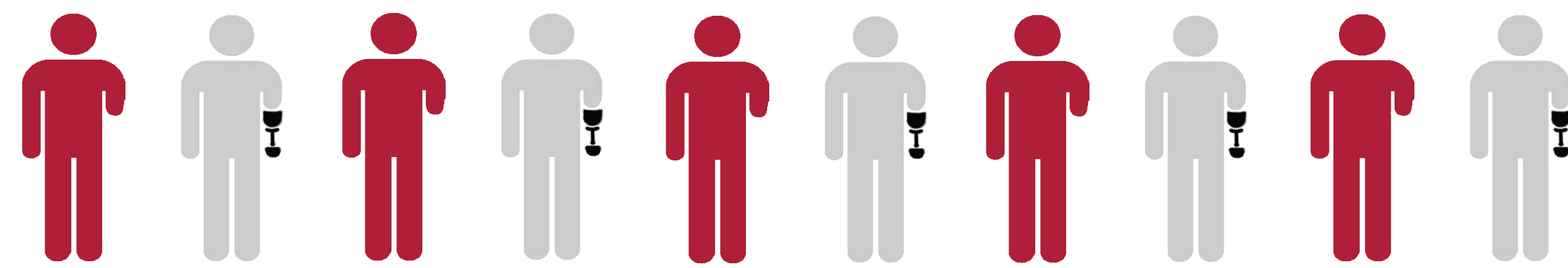
DEPARTMENT OF BIOMEDICAL ENGINEERING

Abigail R. Citterman^{1,2}, Taylor C. Hansen¹, Eric S. Stone¹, Troy N. Tully¹, Christopher M. Baschuk², Christopher C. Duncan³, Jacob A. George^{1,3,4,5}

abbycitt@gmail.com

¹Department of Biomedical Engineering ²Handspring, Salt Lake City, UT ³Department of Physical Medicine and Rehabilitation ⁴Department of Electrical and Computer Engineering ⁵Department of Mechanical Engineering, University of Utah, Salt Lake City, UT

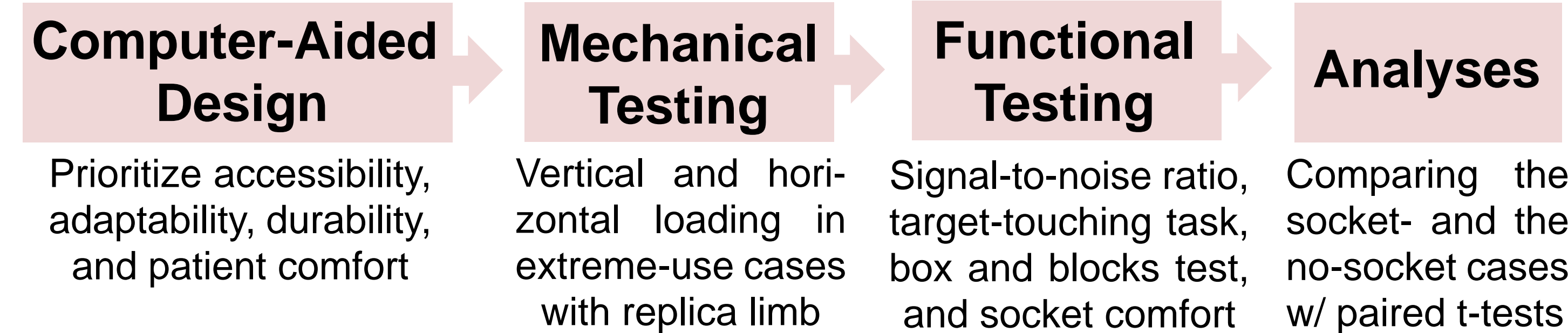
Motivation



Up to 50% of individuals with upper-limb loss abandon their prostheses. More dexterous myoelectric control could improve prosthesis acceptance. However, the validation of novel control strategies is limited by the time, cost, and expertise needed to fabricate a traditional custom-fit socket with embedded electrodes.

The development of a more accessible socket may constitute an important step towards expanding the involvement of those with upper-limb loss in myoelectric control research.

Materials & Methods



Three transradial amputees with high-count surface electromyography (sEMG) control

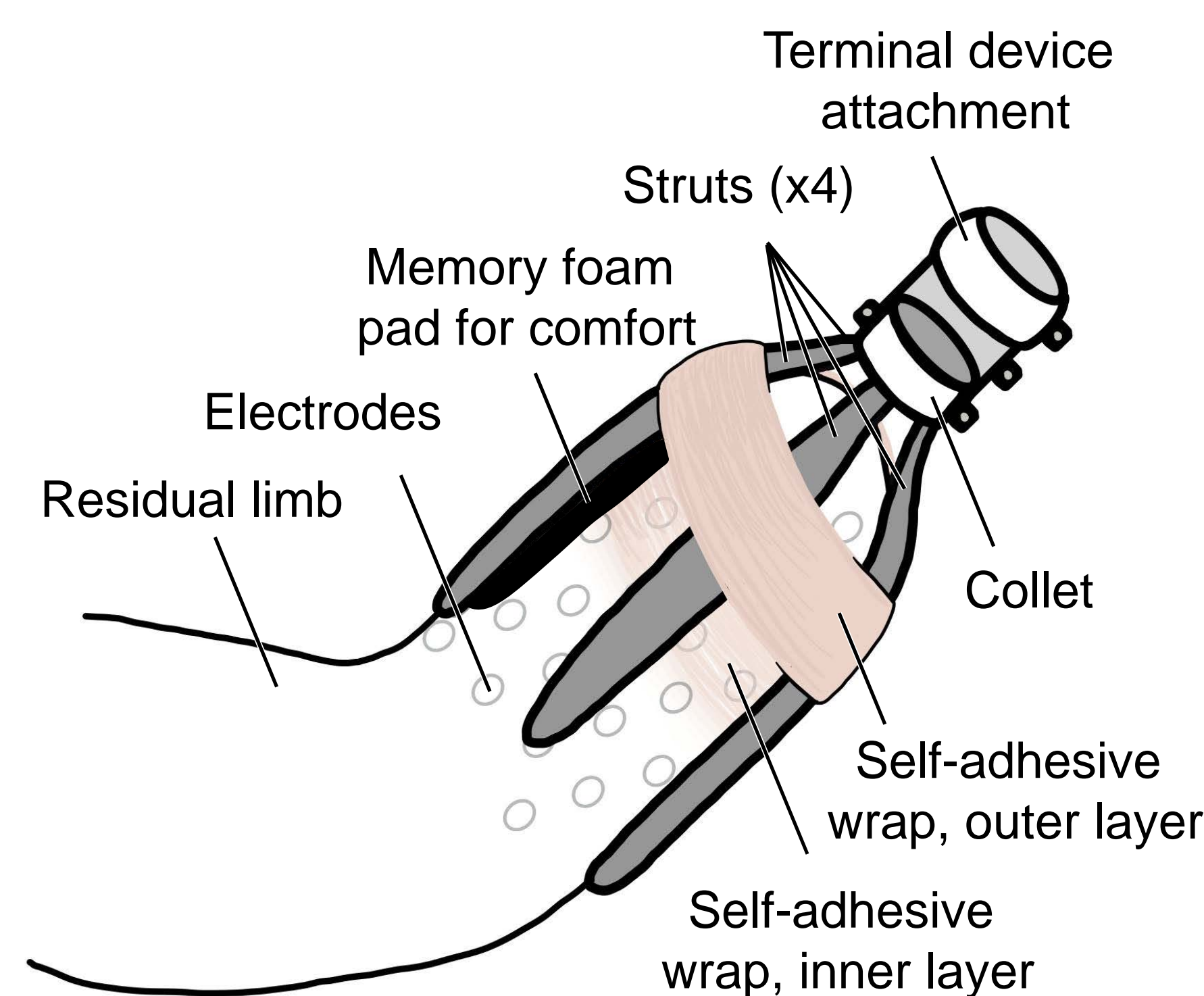


Table 1: Cost Analysis

3D-printed components (i.e., filament)	\$3.50
Hardware (i.e., nuts and bolts)	\$1.00
Self-adhesive wrap	\$3.00
Memory foam	\$0.50
Total	\$8.00
vs	
Traditional socket	\$3,000 ¹
Low-cost alternative	\$200 ²

Device Development

Accessibility

- No prosthetist expertise needed
- Inexpensive, widely-available materials (Table 1)
- No protracted laboratory visits required (Table 2)

Table 2: Time Approximation

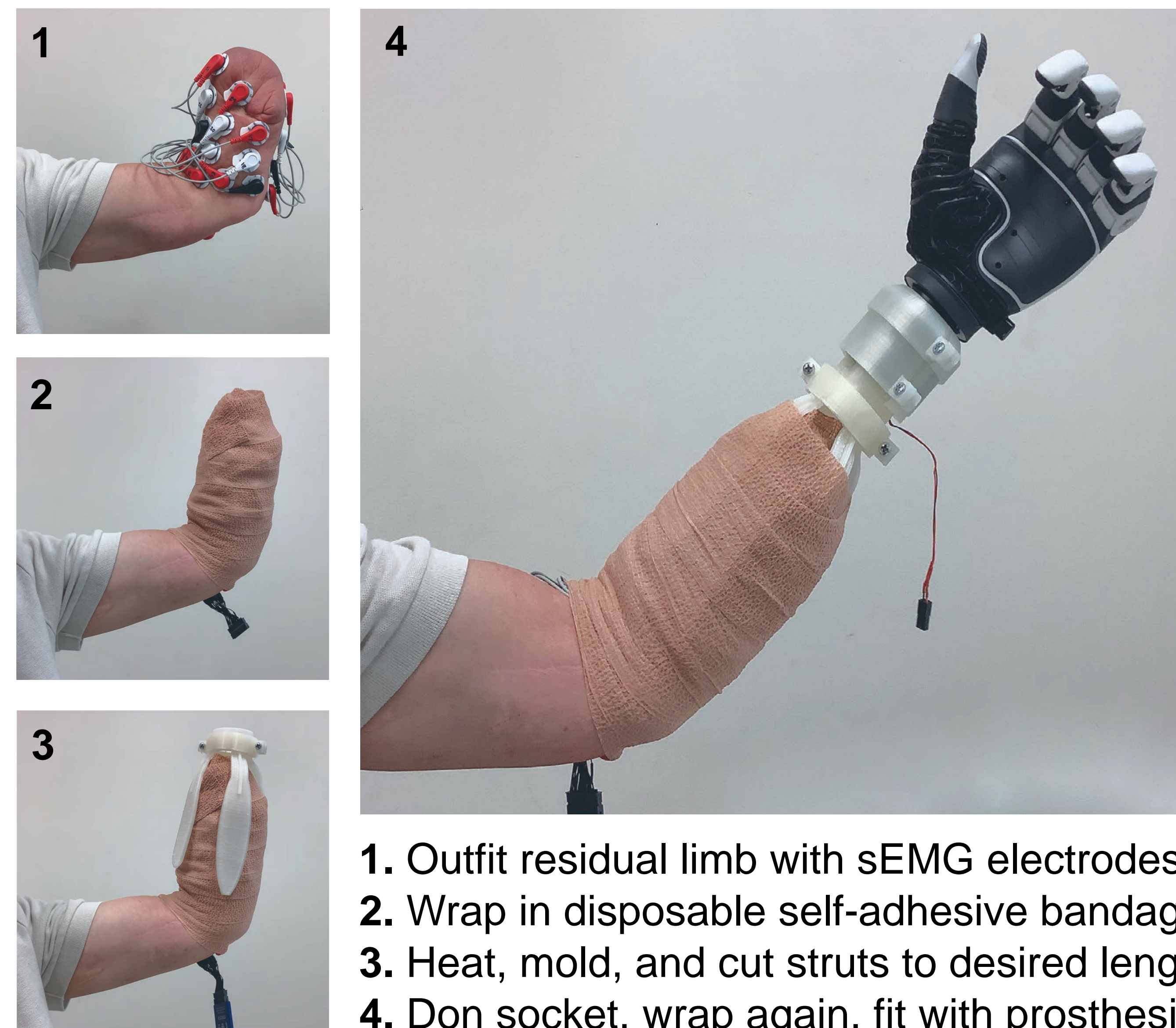
Fabrication (3D printing)	6 hours, 30 minutes
Fitting (molding struts)	10 minutes
Donning	<1 minute
Dooffing	<1 minute

Adaptability

- Access to skin for various data acquisition (DAQ) methods (electromyography, magnetomyography, sonomyography, etc.)
- Moldable struts accommodate limb differences (volume fluctuations, bone protrusions, neuromas, wounds, etc.)
- 3D-printed collet interfaces with any terminal device

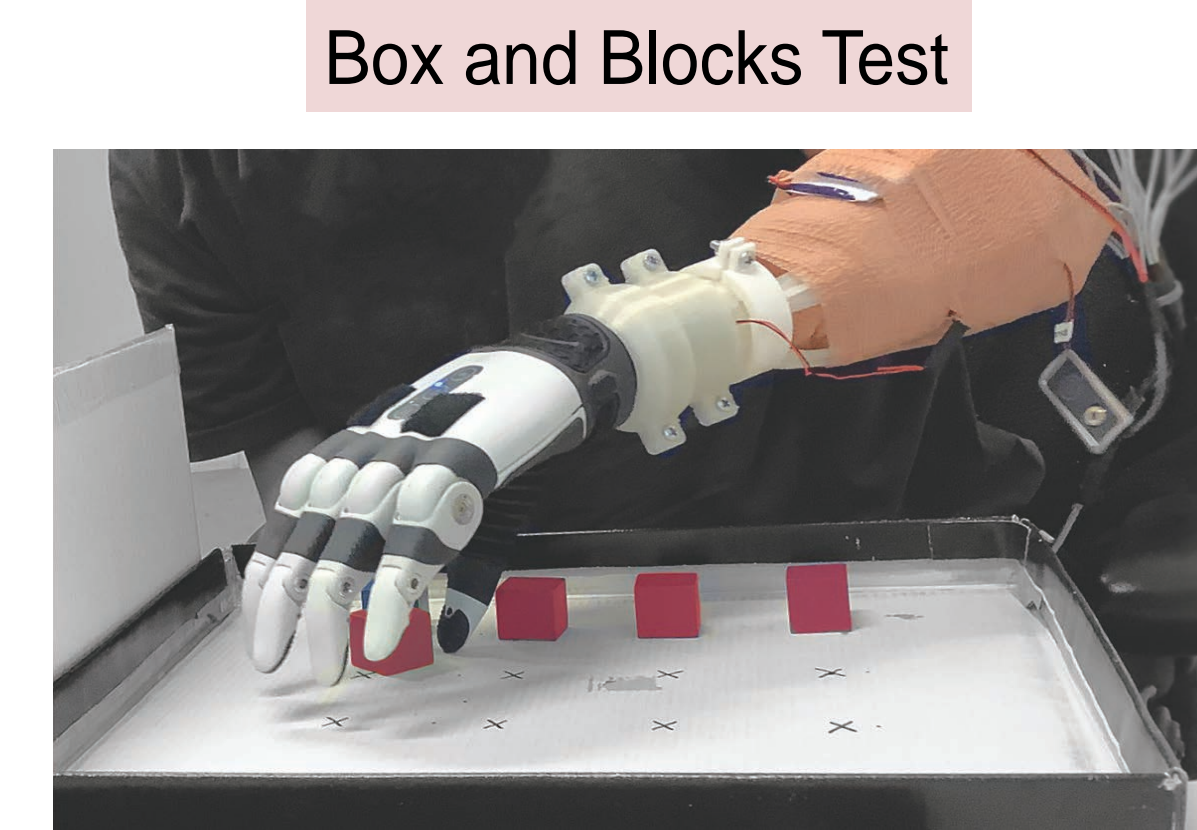
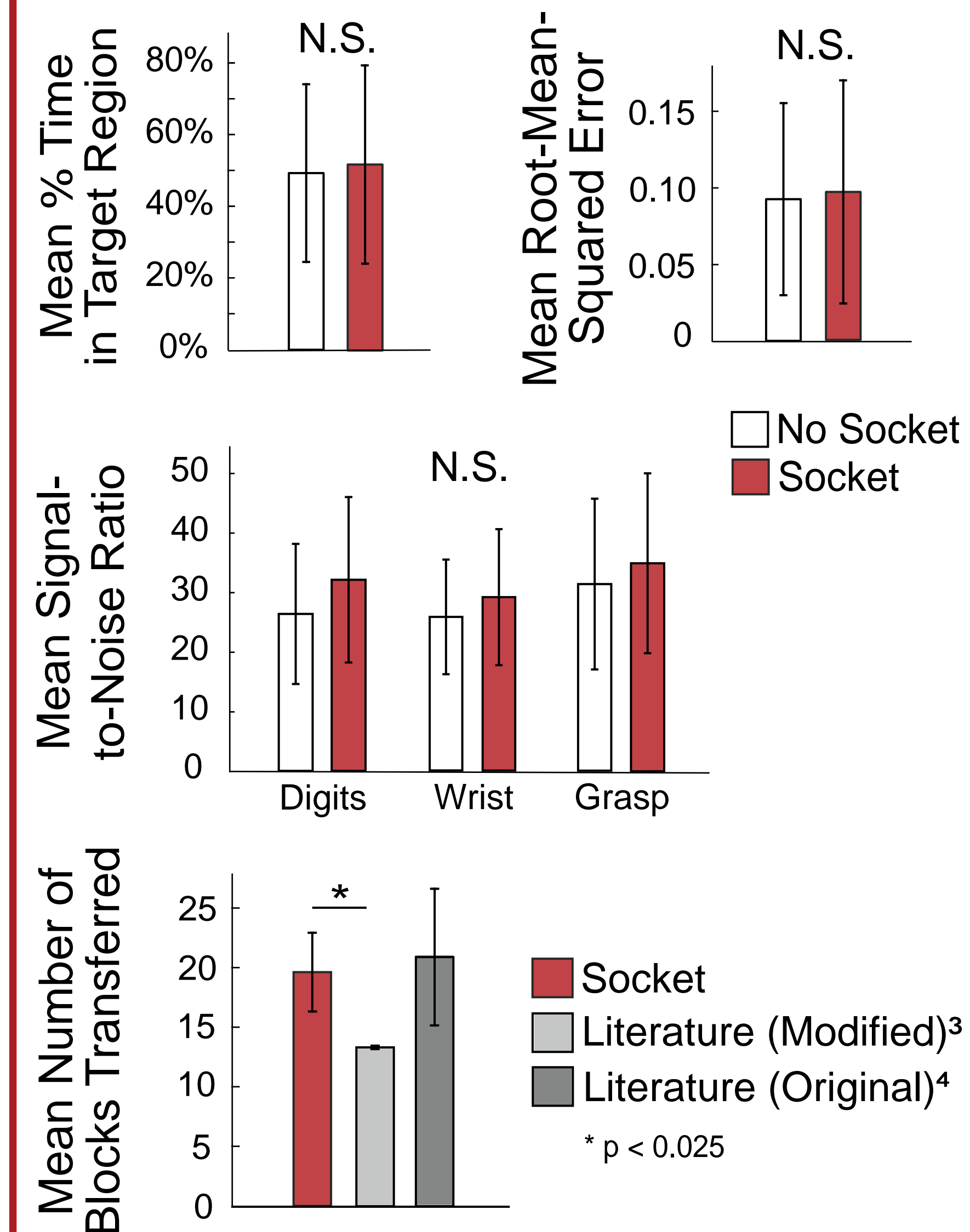
Durability

- Increased surface area distributes weight and pressure
- No slippage and <1° deflection observed with 8 kg load



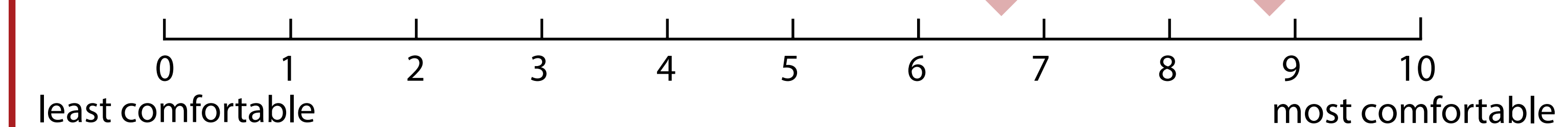
Socket Did Not Impede Functional Performance; Comfort Remained Adequate

Functional Performance Was Not Hindered by Low-Cost Socket.



Socket Comfort Was Acceptable Throughout the Experiment.

Our Socket	Traditional Socket
6.7 ± 1.2	8.8 ± 1.3



Future Work

- To further increase end-user involvement, expand implementation to:
- More varied limb presentations
 - Additional levels of amputation

References & Acknowledgments

- [1] L. Frossard, et al. *J. Prosthet. Orthot.* 2017. [3] J. George, et al. *Sci Robot.* vol. 4. 2019.
 [2] R. Ismail, et al. *Electron.* no. 9: 1456. 2020. [4] S. Salminger, et al. *Am. J. Phys. Med. Rehabil.* 2019.

Funding provided by: A.C.'s UROP Awards, Travel Grant, and Parent Fund Scholarship, and J.A.G.'s NIH 1DP5OD029571-01 Award

